



DUALITY FOR A CLASS OF CONTINUOUS-TIME PROGRAMMING PROBLEMS

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We consider a class of nonlinear continuous-time programming problems and a general Mond-Weir dual model for this class. We get that WD-invexity property is a necessary and sufficient condition for weak duality.

Key words: WD-invexity, continuous-time nonlinear programming, Mond-Weir duality, weak duality.

1. INTRODUCTION

In 1953, Bellman [1] introduced a certain class of continuous-time optimization problems. Since then, many new classes of continuous-time nonlinear problems were considered. See De Oliveira and Rojas-Medar [4], Rojas-Medar *et al.* [5], Zalmai [6] and the references therein.

De Oliveira and Rojas-Medar [4] gave a generalization of the notions of KKT-invexity and WD-invexity for the continuous-time nonlinear programming problem, introduced by Martin [2] for the mathematical programming case. Also, they proved two very interesting results: KKT-invexity is a necessary and sufficient condition for global optimality of a Karush-Kuhn-Tucker point and WD-invexity is a necessary and sufficient condition for weak duality, where a Lagrangian dual (a continuous-time analogue to Wolfe's duality) is considered.

We prove that WD-invexity property of a general Mond-Weir dual for the continuous-time nonlinear programming problem also is a necessary and sufficient condition for weak duality. In this respect, we consider a general WD-invexity concept and a general qualification constraint, generalizations of the notions introduced by Oliveira and Rojas-Medar [4].

2. PRELIMINARIES

We consider the following continuous-time nonlinear programming problem

$$(CNP) \quad \text{minimize } \phi(x) = \int_0^T f(x(t), t) dt$$

subject to

$$g(x(t), t) \leq 0 \text{ a.e. in } [0, T], x \in X,$$

where X is a nonempty open convex subset of the Banach space $L_\infty^n[0, T]$, $\varphi: X \rightarrow \mathbb{R}$, $f(x(t), t) = \zeta(x)(t)$ and $g(x(t), t) = \gamma(x)(t)$, with the mappings ζ and γ from X into $\Lambda_1^1[0, T]$ and $\Lambda_1^m[0, T]$, respectively. Here, $L_\infty^n[0, T]$ is the space of all n -dimensional vector-valued Lebesgue

measurable functions defined on the compact interval $[0, T] \subset \mathbb{R}$ that are essentially bounded, with the norm $\|\cdot\|_\infty$ defined by

$$\|x\|_\infty = \max_{1 \leq j \leq n} \text{esssup} \left\{ |x_j(t)|, 0 \leq t \leq T \right\},$$

where $(x_j(t))_{1 \leq j \leq n} = x(t) \in \mathbb{R}^n$; the space $\Lambda_1^m[0, T]$ is the space of all m -dimensional vector-valued functions defined on $[0, T]$ that are essentially bounded and Lebesgue measurable, with the norm $\|\cdot\|_1$ defined by

$$\|y\|_1 = \max_{1 \leq j \leq n} \int_0^T |y_j(t)| dt$$

for $y(t) = (y_j(t))_{1 \leq j \leq n} \in \mathbb{R}^n$.

Let $F = \{x \in X : g(x(t), t) \leq 0 \text{ a.e. in } [0, T]\}$ be the set of all feasible solutions of (CNP). We suppose that F is a nonempty set and all vectors are column vectors. For $w \in \mathbb{R}^p$, $w \leq 0$ means that $w_i \leq 0$ for all $i=1, 2, \dots, p$; $w < 0$ means that $w_i < 0$ for $i=1, 2, \dots, p$ and w' stands for the transposed of w .

Now, for (CNP) problem, we consider a general Mond-Weir dual. We suppose that the functions $t \mapsto \nabla f(x(t), t)$ and $t \mapsto \nabla g_i'(x(t), t)z(t), i \in I = \{1, 2, \dots, p\}$, are Lebesgue integrable in $[0, T]$ for all $x \in X$ and for all $z \in L_\infty^n[0, T]$. The general Mond-Weir type dual is

$$(MWDP) \quad \text{maximize } \psi(x, \lambda) = \int_0^T \left[f(x(t), t) + \lambda'_{I_0}(t) g_{I_0}(x(t), t) \right] dt$$

subject to

$$\begin{aligned} \int_0^T \left[\nabla f(x(t), t) + \sum_{i \in I} \lambda_i(t) \nabla g_i'(x(t), t) \right] z(t) dt &= 0, \\ \lambda_{I_k}'(t) g_{I_k}(x(t), t) &\geq 0 \text{ a.e. in } [0, T], \quad k = \overline{1, \nu}, \\ \lambda_i(t) &\geq 0 \text{ a.e. in } [0, T], \quad i \in I, \\ z &\in L_\infty^n[0, T], \quad x \in X, \quad \lambda \in L_\infty^m[0, T], \end{aligned}$$

where $\nu \geq 0, I_\alpha \cap I_\beta = \Phi$ for $\alpha \neq \beta$ and $\bigcup_{\alpha=0}^\nu I_\alpha = \{1, \dots, m\}$, $\lambda_{I_k} = (\lambda_i)_{i \in I_k}$ and $g_{I_k} = (g_i)_{i \in I_k}$ with

$$\lambda_{I_k}'(t) g_{I_k}(x(t), t) = \sum_{i \in I_k} \lambda_i'(t) g_i(x(t), t).$$

This dual problem (MWDP) may be considered as the continuous-time analogue of a general Mond-Weir duality formulation [3].

Let **FD** denote the set of all feasible solutions of (MWDP).

3. INVEXITY AND WEAK DUALITY

Definition 3.1. ([4]) There is weak duality between the problems (CNP) and (MWDP) if

$$\varphi(x) \geq \psi(y, \lambda)$$

for all $x \in F$ and all $(y, \lambda) \in \mathbf{FD}$.

Definition 3.2. ([4]) The (CNP) problem is said to be invex if there exists a function $\eta: V \times V \times [0, T] \rightarrow \mathbb{R}^n$ such that $t \mapsto \eta(x(t), y(t), t) \in L_\infty^n [0, T]$ and

$$\begin{aligned} \varphi(x) - \varphi(y) &\geq \int_0^T \nabla f'(y(t), t) \eta(x(t), y(t), t) dt, \\ g(x(t), t) - g(y(t), t) &\geq \nabla g_i'(y(t), t) \eta(x(t), y(t), t) \quad \text{a.e. in } [0, T], \quad i \in I, \end{aligned}$$

for all $x \in F$ and $y \in X$.

Theorem 3.1. The invexity of (CNP) implies the weak duality between (CNP) and (MWDP).

We note that the omission of the terms $g_i(x(t), t)$, $i \in I$ and $g_i(y(t), t)$, $i \in I_0$ in the last inequality from Definition 3.2 does not affect the conclusion of Theorem 3.1. Thus, this makes it possible to use a generalized WD-invexity for (CNP).

4. GENERALIZED WD- INVEXITY AND WEAK DUALITY

In this section we introduce a generalized WD-invexity and a generalized constraint qualification. Then we prove the equivalence of weak duality for (CNP) and generalized WD-invexity defined below.

Definition 4.1. We say that the (CNP) problem is generalized weak duality invex (generalized WD-invex) if there exists a function $\eta: V \times V \times [0, T] \rightarrow \mathbb{R}^n$ such that $t \mapsto \eta(x(t), y(t), t) \in L_\infty^n [0, T]$ and

$$\begin{aligned} \varphi(x) - \varphi(y) &\geq \int_0^T \nabla f'(y(t), t) \eta(x(t), y(t), t) dt, \\ -g_i(y(t), t) &\geq \nabla g_i'(y(t), t) \eta(x(t), y(t), t) \quad \text{a.e. in } [0, T], \quad i \in I_0, \\ 0 &\geq \nabla g_i'(y(t), t) \eta(x(t), y(t), t) \quad \text{a.e. in } [0, T], \quad i \notin I_0, \end{aligned}$$

for all $x \in F$ and $y \in X$.

Remark 4.1. For $\nu = 0$ generalized WD-invexity reduces to WD-invexity defined in [4].

Definition 4.2. We say that g satisfies the generalized constraint qualification (GCQ) if there is no $v_i \in L_\infty [0, T]$, $v_i(t) \geq 0$ a.e. in $[0, T]$, $i \in I_0$, not all zero, such that

$$\int_0^T \sum_{i \in I_0} v_i(t) g_i(x(t), t) dt \geq 0 \quad \text{for all } x \in X.$$

Remark 4.2. For $I_k = \Phi, k = \overline{1, \nu}$, (GCQ) becomes (CQ2) introduced in [4].

Theorem 4.1. Under (GCQ), weak duality holds between (CNP) and (GMWDP) if and only if (CNP) is generalized WD-invex.

5. CONCLUSION

In this note we proved that in the context of continuous-time nonlinear programming problem, weak duality is attained if the general Mond-Weir dual of the problem previously mentioned has the WD-invexity property. On account of the importance and accuracy of the results from [4], we think that it is interesting and useful to establish corresponding formulations for both the multiobjective continuous case and the case where invexity is replaced by, for example, ρ -invexity.

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